c-pro 3 giga

Programmable controllers (up to 43 I/O)





PLEASE READ CAREFULLY CONSIDER THE ENVIRONMENT

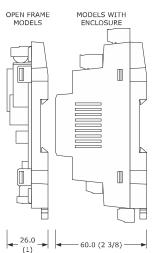
- blind open frame models or with enclosure
- power supply 115... 230 VAC
- 3 dry contact digital inputs
- 2 high voltage digital inputs 4 analogue outputs, 8 in the plus controllers
- 9 electro-mechanical relay digital outputs, 14 in the plus controllers, 11 in the U-EEV

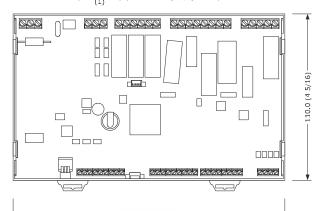
10 analogue inputs, 16 in the plus controllers (can be configured also for dry contact

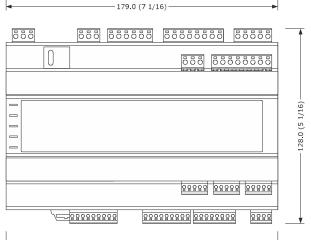
- TTL MODBUS port INTRABUS port (RS-485 MODBUS master/slave by connecting the serial interface
- EVIF22ISX)
- RS-485 MODBUS slave port
- RS-485 port (MODBUS master/slave, BACnet MS/TP) (1)
- CAN port
- models with 2 integrated unipolar stepper electronic expansion valves driver
- models with Ethernet port (MODBUS TCP, WebServer, BACnet IP) (1)
- the BACnet communication protocol can be used only in alternative to the Web Server

Kind of controller	Purchasing codes	Version	Power supply	I/O	Kind of integrated electronic expansion valves driver	Comm. ports
standard	EPG9O	blind open frame		28	none	
standard	EPG9B	blind with enclosure		28	none	TTL,
plus	EPG9BXQ	blind with enclosure		43	none	INTRABUS, 2 RS-485, CAN and
plus	EPG9BHQ	blind with enclosure		43	none	USB
U-EEV	EPG9BXU	blind with enclosure	115 230	36	2 unipolar stepper type	
standard	EPG9OHX	blind open frame	VAC	28	none	
standard	EPG9BHX	blind with enclosure		28	none	TTL, INTRABUS,
plus	EPG9BXP	blind with enclosure		43	none	2 RS-485, CAN,
plus	EPG9BHP	blind with enclosure		43	none	USB and Ethernet
U-EEV	EPG9BHU	blind with enclosure		36	2 unipolar stepper type	

MEASUREMENTS AND INSTALLATION

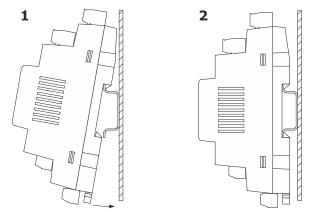




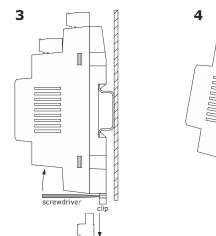


— 179.0 (7 1/16) –

To install the device operate as shown in pictures 1 and 2



To remove the device, first remove any screw-in removable terminal blocks mounted in the



INSTALLATION PRECAUTIONS

- Ensure that the working conditions are within the limits stated in the TECHNICAL SPECIFICATIONS section
- Do not install the device close to heat sources, equipment with a strong magnetic field, in places subject to direct sunlight, rain, damp, excessive dust, mechanical vibrations
- In compliance with safety regulations, the device must be installed properly to ensure adequate protection from contact with electrical parts. All protective parts must be fixed in such a way as to need the aid of a tool to remove them

2 ELECTRICAL CONNECTION



- To reduce any electromagnetic interference connect the power cables as far away as possible from the signal cables and, if necessary, connect to a RS-485 MODBUS network and/or a CAN network by using a twisted pair

2.1.1 Connectors available both in standard and plus controllers Description of connectors

N. DESCRIPTION

N. DESCRIPTION

N. DESCRIPTION NO1 K1 digital output normally open contact (3 A res. @ 250 VAC) CO1 K1 digital output common contact NO2 K2 digital output normally open contact (3 A res. @ 250 VAC) N. DESCRIPTION

CO2 K2 digital output common contact NO3 K3 digital output normally open contact (3 A res. @ 250 VAC) CO3 K3 digital output common contact

NO4 K4 digital output normally open contact (3 A res. @ 250 VAC) CO4 K4 digital output common contact

V~ device power supply (115... 230 VAC)

V~ device power supply (115... 230 VAC)

COM high voltage digital inputs common contact

DIHV1 high voltage digital input; DI1

DIHV2 high voltage digital input; DI2

NO5 K5 digital output normally open contact (2 A res. @ 250 VAC)

CO5 K5 digital output common contact NO6 K6 digital output normally open contact (3 A res. @ 250 VAC)

CO6 K6 digital output common contact

NO7 K7 digital output normally open contact (8 A res. @ 250 VAC)

CO7 K7 digital output common contact

N. DESCRIPTION

CO8 K8 digital output common contact

NC9 K9 digital output normally closed contact NO9 K9 digital output normally open contact (3 A res. @ 250 VAC)

CO9 K9 digital output common contact

N. DESCRIPTION

CAN+ signal + CAN port CAN- signal - CAN port

A1/+ signal + RS-485 MODBUS slave port

B1/- signal - RS-485 MODBUS slave port

A2/+ signal + RS-485 port (MODBUS master/slave, BACnet MS/TP)

B2/- signal - RS-485 port (MODBUS master/slave, BACnet MS/TP)

IB data INTRABUS port GND reference (GND)

12V power supply remote user interfaces (13 VDC)

The actual UNI-PRO 3.13 version implements a BACnet® standardized device profile B-ASC which doesn't require the managing of Scheduler and Calendar objects, instead required for the

N. DESCRIPTION

GND reference (GND)

DI3 digital input 3 (dry contact and for pulse trains up to 2 KHz); DI3

DI4 digital input 4 (dry contact and for pulse trains up to 2 KHz); DI4 DI5 digital input 5 (dry contact and for pulse trains up to 2 KHz); DI5

All analogue input 1 (for PTC, NTC or Pt 1000 probes); All

can be configured also for dry contact digital input Al2 analogue input 2 (for PTC, NTC or Pt 1000 probes); Al2 can be configured also for dry contact digital input

analogue input 3 (for PTC, NTC or Pt 1000 probes); AI3

can be configured also for dry contact digital input analogue input 4 (for PTC, NTC or Pt 1000 probes); AI4

can be configured also for dry contact digital input analogue input 5 (for PTC, NTC or Pt 1000 probes); AI5 can be configured also for dry contact digital input

N. DESCRIPTION GND reference (GND)

analogue input 6 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI6 can be configured also for dry contact digital input

analogue input 7 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI7

can be configured also for dry contact digital input

analogue input 8 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); A18 can be configured also for dry contact digital input

analogue input 9 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers): A19

can be configured also for dry contact digital input analogue input 10 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI10

can be configured also for dry contact digital input

+5V power supply 0-5 V ratiometric transducers (5 VDC)

VS power supply transducers (13 VDC)

N. DESCRIPTION

AO1 analogue output 1 (for 0-10 V or PWM)

AO2 analogue output 2 (for 0-10 V or PWM) AO3 analogue output 3 (for 0-10 V or PWM)

AO4 analogue output 4 (for 0-10 V or PWM)

2.1.2 Connectors only available in the plus controllers

Description of connectors.

N. DESCRIPTION NO10 K10 digital output normally open contact (8 A res. @ 250 VAC)

CO10 K10 digital output common contact NC10 K10 digital output normally closed contact NO11 K11 digital output normally open contact (2 A res. @ 250 VAC)

CO11 K11 digital output common contact

NO12 K12 digital output normally open contact (2 A res. @ 250 VAC) CO12 K12 digital output common contact

NO13 K13 digital output normally open contact (2 A res. @ 250 VAC) CO13 K13 digital output common contact

NO14 K14 digital output normally open contact (2 A res. @ 250 VAC) CO14 K14 digital output common contact

N. DESCRIPTION (for models EPG9BXP and EPG9BHP)

GND reference (GND)

AO5 analogue output 5 (for 0-10 V or PWM)

AO6 analogue output 6 (for 0-10 V or PWM)

AO7 analogue output 7 (for 0-10 V or PWM) AO8 analogue output 8 (for 0-10 V or PWM)

N. DESCRIPTION (for models EPG9BXQ and EPG9BHQ)

GND reference (GND)

DI6 digital input 6 (dry contact); DI6

DI7 digital input 7 (dry contact); DI7 DI8 digital input 8 (dry contact); DI8

DI9 digital input 9 (dry contact); DI9

2.1.3 Connectors only available in the U-EEV controllers

Description of connectors.

N. DESCRIPTION

NO10 | K10 digital output normally open contact (5 A res. @ 250 VAC) CO10 K10 digital output common contact

NO11 K11 digital output normally open contact (5 A res. @ 250 VAC) CO11 K11 digital output common contact

power supply engine unipolar stepper electronic expansion valve 1 (12 VDC, 260 mA max. winding)

OUT4 output 4 unipolar stepper electronic expansion valve 1 engine control

OUT3 output 4 unipolar stepper electronic expansion valve 1 engine control

OUT2 output 4 unipolar stepper electronic expansion valve 1 engine control OUT1 output 4 unipolar stepper electronic expansion valve 1 engine control

N. DESCRIPTION

power supply engine unipolar stepper electronic expansion valve 2 (12 VDC, 260 mA REF max. winding)

OUT4 output 4 unipolar stepper electronic expansion valve 2 engine control OUT3 output 4 unipolar stepper electronic expansion valve 2 engine control

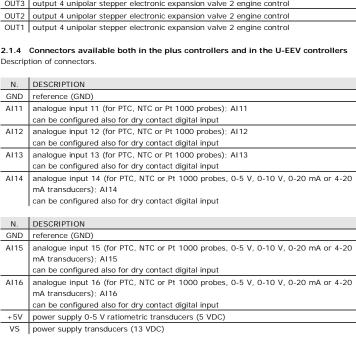
Description of connectors

analogue input 12 (for PTC, NTC or Pt 1000 probes)

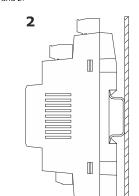
mA transducers); AI14 can be configured also for dry contact digital input

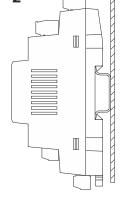
Al15 analogue input 15 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20

analogue input 16 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI16

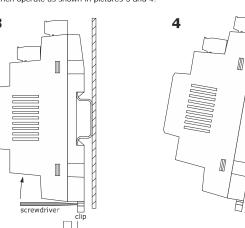








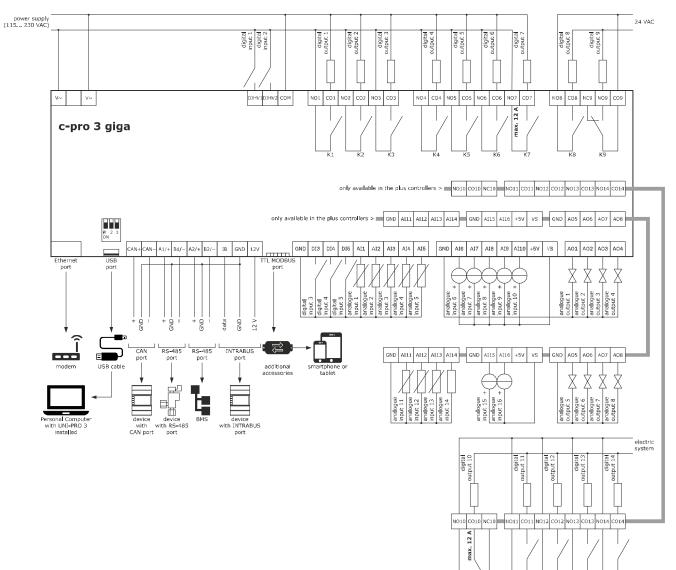




o	install	the	device	again	press	down	the	clip	before	

Electrical connection 2.2

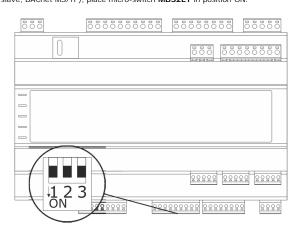
Example of electrical connection for standard and plus controllers.



Fitting the termination resistor of RS-485 networks and CAN network

To fit the CAN network termination resistor, place micro-switch ${\bf CANLT}$ in position ON. To fit the termination resistor of the RS-485 network connected to the RS-485 MODBUS slave

port, place micro-switch MBS1LT in position ON. To fit the termination resistor of the RS-485 network connected to the RS-485 port (MODBUS master/slave, BACnet MS/TP), place micro-switch MBS2LT in position ON.



PRECAUTIONS FOR ELECTRICAL CONNECTION

- If using an electrical or pneumatic screwdriver, adjust the tightening torque If the device has been moved from a cold to a warm place, the humidity may have
- caused condensation to form inside. Wait about an hour before switching on the power Make sure that the supply voltage, electrical frequency and power are within the set limits. See the section TECHNICAL SPECIFICATIONS
- Disconnect the power supply before doing any type of maintenance Do not use the device as safety device

	- Do not use the device as safety device					
 For repairs and for further information, contact the EVCO sales network. 						
3 TECHNICAL SPECIFIC	ATLONG					
3 TECHNICAL SPECIFIC	ATTONS					
Purpose of the control device:		Function contro	oller.			
Construction of the control dev	ire.	Built-in electro				
Container:	100.	Grey, self-extir				
Category of heat and fire resist	tance.	D.	.ga.sg.			
Measurements:		[Б.				
10 DIN modules: 179.0 x 110	0.0 x 26.0 mm	10 DIN modules: 179.0 x 128.0 x 60.0 mm				
(7 1/16 x 4 5/16 x 1 in) th		(7 1/16 x 5 1/16 x 2 3/8 in) the models with				
models		enclosure.				
Mounting methods for the cont	rol device:	To be fitted on	a DIN rail, in a control panel.			
Degree of protection provided	by the covering:	•	·			
IP00 the open frame models		IP40 the front	of the models with enclosure.			
Connection method:						
screw terminal blocks for wi	res up to 1.5	removable scre	ew terminal blocks for wires up			
mm ² and 2.5 mm ² the open fr	ame models	to 1.5 mm ² a	nd 2.5 mm ² the models with			
		enclosure				
removable clamp terminal bloc	ks for wires up	Pico-Blade connector				
to 1.5 mm² the plus controllers	S					
Micro-USB connector		RJ45 F telepho	ne connector (according to the			
		model).				
Maximum permitted length for connection cables:						
Power supply: 10 m (32.8 ft)		Analogue input	s: 10 m (32.8 ft)			
Auxiliary power supply and 0-	5 V ratiometric	Digital inputs:	10 m (32.8 ft)			
transducer power supply: 10 m						
0-10 V analogue outputs: 10 n	n (32.8 ft)	PWM analogue	outputs: 1 m (3.28 ft)			
Digital outputs: 100 m (328 ft)			t: 10 m (32.8 ft)			
Unipolar stepper electronic exp	ansion valves d					
RS-485 MODBUS port: 1,000 r		USB port: 1 m	· · · · · · · · · · · · · · · · · · ·			
CAN port:	1,000 m (3,28)	0 ft), baud rate: 20,000 baud				
	500 m (1,640 f		t), baud rate: 50,000 baud			
	250 m (820 ft)	, baud rate: 125,000 baud				
	50 m (164 ft),	baud rate: 500,000 baud.				
Operating temperature:		From -10 to 55 °C (from 14 to 131 °F).				
Storage temperature:		From -20 to 70 °C (from -4 to 158 °F).				
Operating humidity:		Relative humidity without condensate from 5 to 95%.				
Pollution status of the control of	device:	2.				
Compliance:						
RoHS 2011/65/EC	WEEE 2012/19	P/EU	REACH (EC) Regulation no. 1907/2006			
EMC 2014/30/EU		LVD 2014/35/L	JE.			
<u> </u>						

		K10	K11	K12	K13	K14	
Power supply:			115	230	VAC (+	10% -15%), 50/60 Hz	
						, 20 VA in the plus con-	
Earthing methods for the control device:				s, 27 V	A in the	U-EEV controllers.	
	withstand voltage		None. 2.5 K\	1.			
Over-voltage c		.	11.				
Software class	and structure:		A.				
Clock:						m battery.	
Clock drift:	autonomy in the	a absonce of a			at 25°C		
power supply:	autonomy in the	e absence or a	> 6 months at 25 °C (77 °F).				
Clock battery of	harging time:		24h (the battery is charged by the power supply of the device).				
Analogue input	is:		5 for	PTC, N	ITC or Pt	1000 probes, 8 in the	
			plus controllers and in the U-EEV controllers (can be configured also for dry contact digital				
			input)				
			5 for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers, 8 in				
			I			nd in the U-EEV control-	
			lers (can be configured also for dry contact digital input).				
PTC probes:	Sensor type:					25 °C, 77 °F)	
	Measurement f	ield:				rom -58 to 302 °F)	
NTO	Resolution:			(1 °F)		0 77 %5\	
NTC probes:	Sensor type: Measurement f	ield:		_		C, 77 °F) rom -58 to 248 °F)	
	Resolution:			(1 °F)			
Pt 1000	Sensor type:		1 KΩ @ 0 °C, 32 °F				
probes:	Measurement f	ield:	from -100 to 400 °C (from -148 to 752 °F)				
0.5.1/ +====	Resolution:		1 °C (1 °F). ≥ 10 KΩ				
0-5 V trans- ducers:	Input resistant Resolution:	.e.	0.01 V.				
0-10 V trans-	Input resistance	e:	≥ 10 KΩ				
ducers:	Resolution:		0.01 \	/ .			
0/4-20 mA	Input resistance	e:	≤ 200				
transducers:	Resolution:	rface.	0.01 r		0/ 100/	150 mA may	
Power supply t	emote user inte ransducers:	riaces:				5, 150 mA max. -10%, 100 mA max.	
			I			plus controllers, 60 mA	
			in the U-EEV controllers).				
Power supply 0)-5 V ratiometric	transducers:	5 VDC, ±15 %, 20 mA max. (+40 mA max. in the plus controllers).				
Digital inputs:			3 dry contact and for pulse trains up to 2 KHz				
			2 high voltage.				
Dry contact:		Contact type:	3.3 VDC, 1 mA			DC, 1 mA	
10.1		Power supply:	115 230 VAC.		000 1/40		
High voltage co	er electronic ex	Power supply: pansion valves	accord	dina to		. 230 VAC. del, 2 (12 VDC, 260 mA	
driver:			max. winding).				
Analogue outputs:			4 for 0-10 V or PWM signal, 8 in the plus controllers				
0-10 V sig-	Minimum app	licable imped-	1 ΚΩ				
nal:	ance: Resolution:		0.01 V.				
PWM signal:	Power supply:				10 mA n	nax.	
	Frequency:			2 KI	łz		
	Duty: Resolution:		0 10) Hz E0/	up to 2 KHz	
Digital outputs:			1% up to 500 Hz, 5% up to 2 KHz. 2 with SPST electro-mechanical relay, 2 A				
			res. @ 250 VAC, 6 in the plus controllers				
			I			-mechanical relay, 3 A	
			res. @ 250 VAC				
			1 with SPDT electro-mechanical relay, 3 A res. @ 250 VAC, 2 in the plus controllers				
			2 with SPST electro-mechanical relay, 5 A				
			res. @ 250 VAC, only available in the U-EEV				
				controllers 1 with SPST electro-mechanical relay, 8 A			
				res. @ 250 VAC.			

res. @ 250 VAC

reinforced insulation between "group 1" of relay outputs (K1... K3) and high voltage digital

The device guarantees

inputs (DIHV1 and DIHV2)

- reinforced insulation between SELV circuits and relay outputs

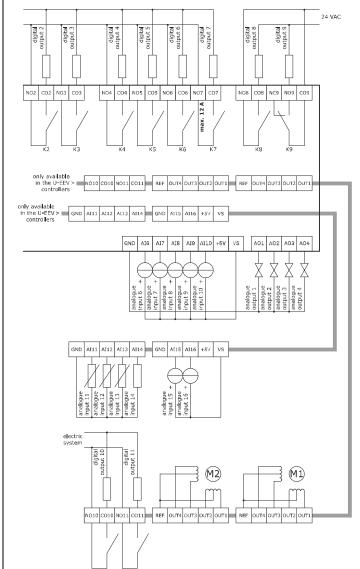
basic insulation between relay outputs belonging to the same group

basic insulation between live parts of opposite polarity (line-neutral).

- reinforced insulation between "groups" of relay outputs

reinforced insulation between live parts and SELV circuits

Example of electrical connection for U-EEV controllers



KIO KII	
Type 1 or Type 2 Actions:	Type 1.
Additional features of Type 1 or Type 2 ac-	C.
tions:	
Communications ports:	
1 TTL MODBUS port	1 INTRABUS port (RS-485 MODBUS mas-
	ter/slave by connecting the serial interface
	EVIF22ISX)
1 RS-485 MODBUS slave port	1 RS-485 port (MODBUS master/slave, BAC-
	net MS/TP)
1 CAN port	1 USB port

according to the model, Ethernet port (MODBUS TCP, WebServer, BACnet IP).

The device must be disposed of according to local regulations governing the collection of electrical and electronic waste.

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